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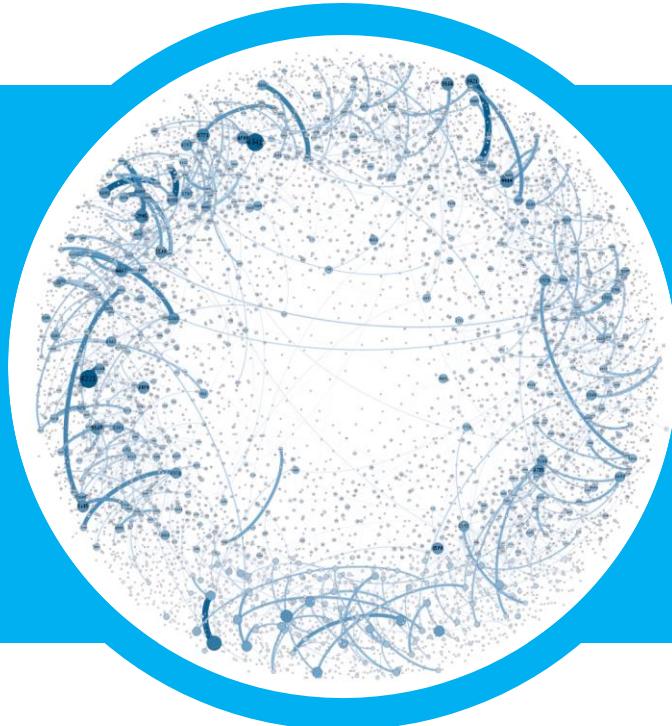


Network GPS – Navigating network dynamics

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אוניברסיטת בר-אילן

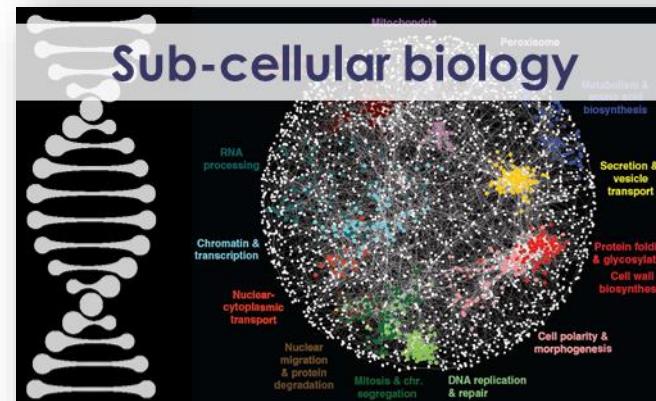
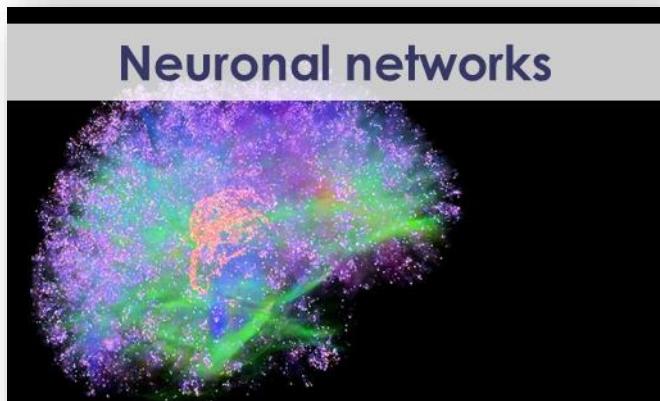




2003 NORTHEAST BLACKOUT

5.5×10^7 People affected
 10^2 Fatalities
 6×10^9 USD in damages

Crucial role of networks



Going beyond mapping

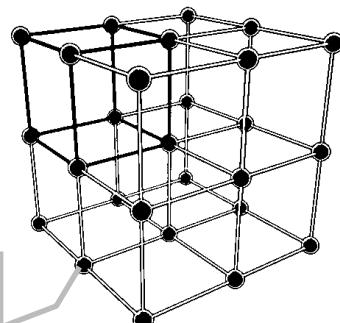


Going beyond mapping



The challenge of networks

Statistical physics comfort zone:



Each node has
 $k = 6$ nearest
neighbors

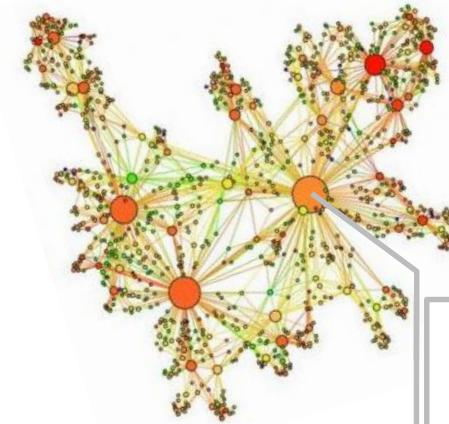
- Low dimensional
- Symmetric structures (lattice or lattice-like)

Finite dimension: $\langle d \rangle \sim \sqrt[{\text{Dim}}]{N}$

Degree distribution: bounded $P(k) \sim e^{-k}$

Hamiltonian dynamics

Where real networks are:



k spans
orders of
magnitude

- Disordered and weighted (for now: positive)
- Heterogeneous – Hubs and small nodes

Small world (infinite dimension): $\langle d \rangle \sim \log N$

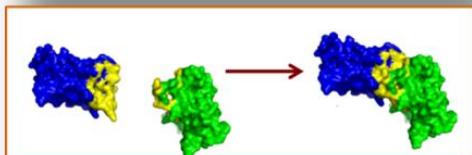
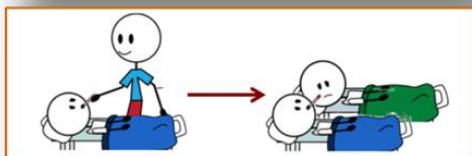
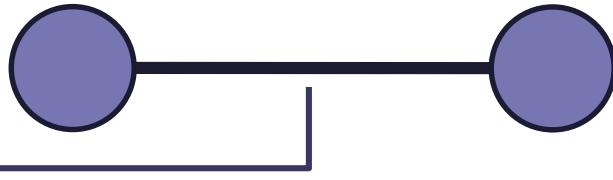
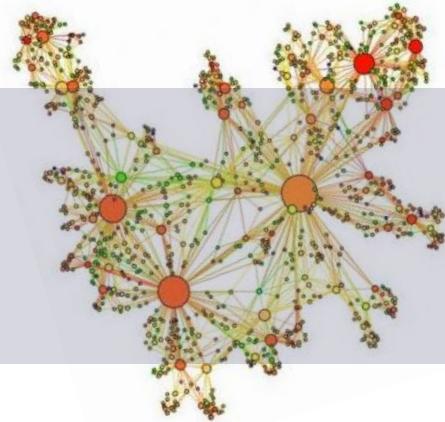
Degree distribution: scale free $P(k) \sim k^{-\gamma}$

Nonlinear dynamics (sometimes hidden)

Dynamics layer

$x_i(t) \rightarrow \text{Activity}$

$$\frac{dx_i}{dt} = \mathbf{M}_0(x_i) + \sum_{j=1}^N A_{ij} \mathbf{M}_1(x_i) \mathbf{M}_2(x_j)$$



A_{ij} Weighted, directed topology

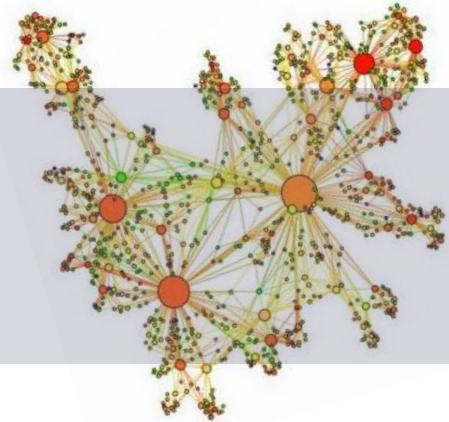
$x_i(t)$ Concentration, Infection probability, Species abundance

M_0, M_1, M_2 Intrinsic nonlinear interaction mechanisms

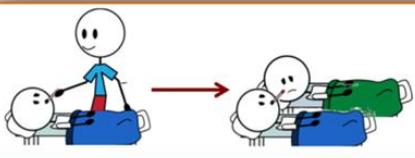
Dynamics layer

$x_i(t) \rightarrow \text{Activity}$

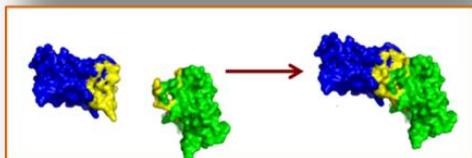
$$\frac{dx_i}{dt} = \mathbf{M}_0(x_i) + \sum_{j=1}^N A_{ij} \mathbf{M}_1(x_i) \mathbf{M}_2(x_j)$$



$$\frac{dx_i}{dt} = Bx_i(1 - x_i) + \sum_{j=1}^N A_{ij} \frac{x_i x_j^a}{1 + x_j^a}$$

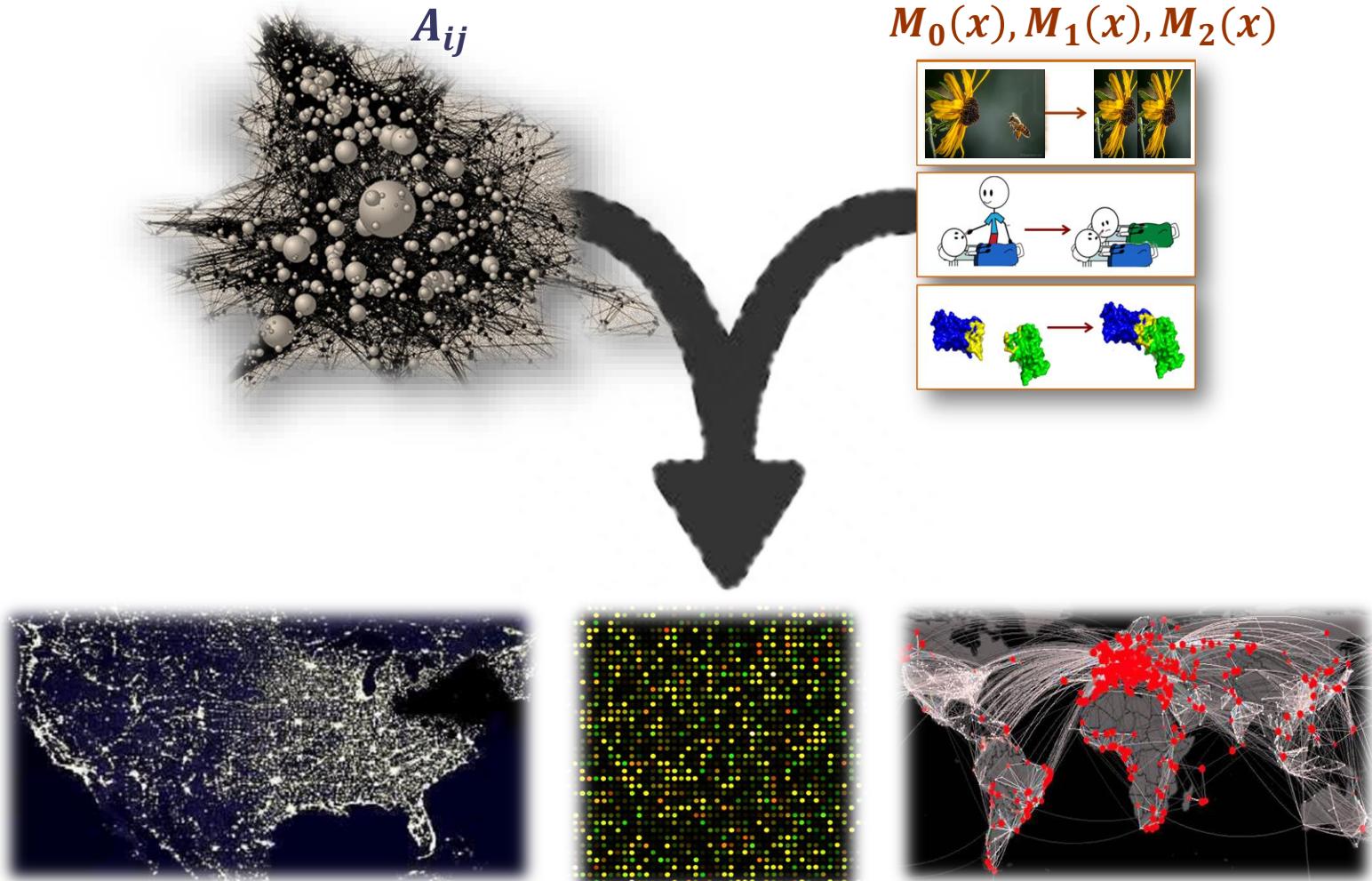


$$\frac{dx_i}{dt} = -Bx_i + \sum_{j=1}^N A_{ij}(1 - x_i)x_j$$



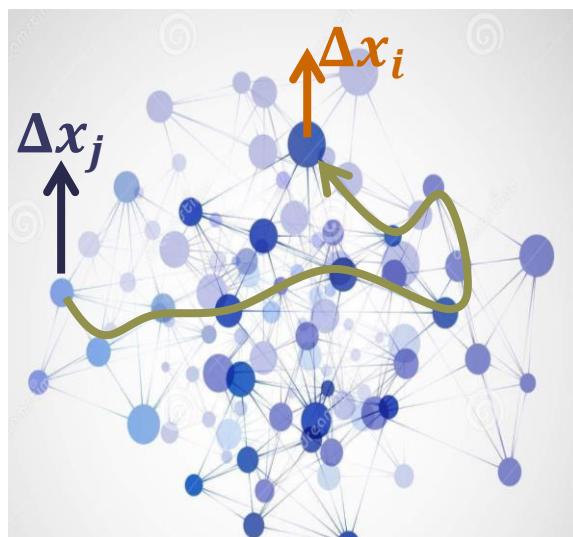
$$\frac{dx_i}{dt} = -Bx_i + \sum_{j=1}^N A_{ij} \frac{x_j^h}{1 + x_j^h}$$

Bringing networks to life



patterns of information spread

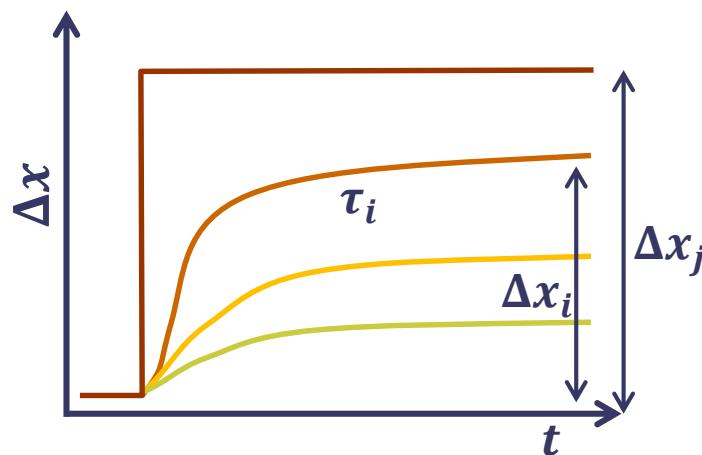
Information flow in complex networks



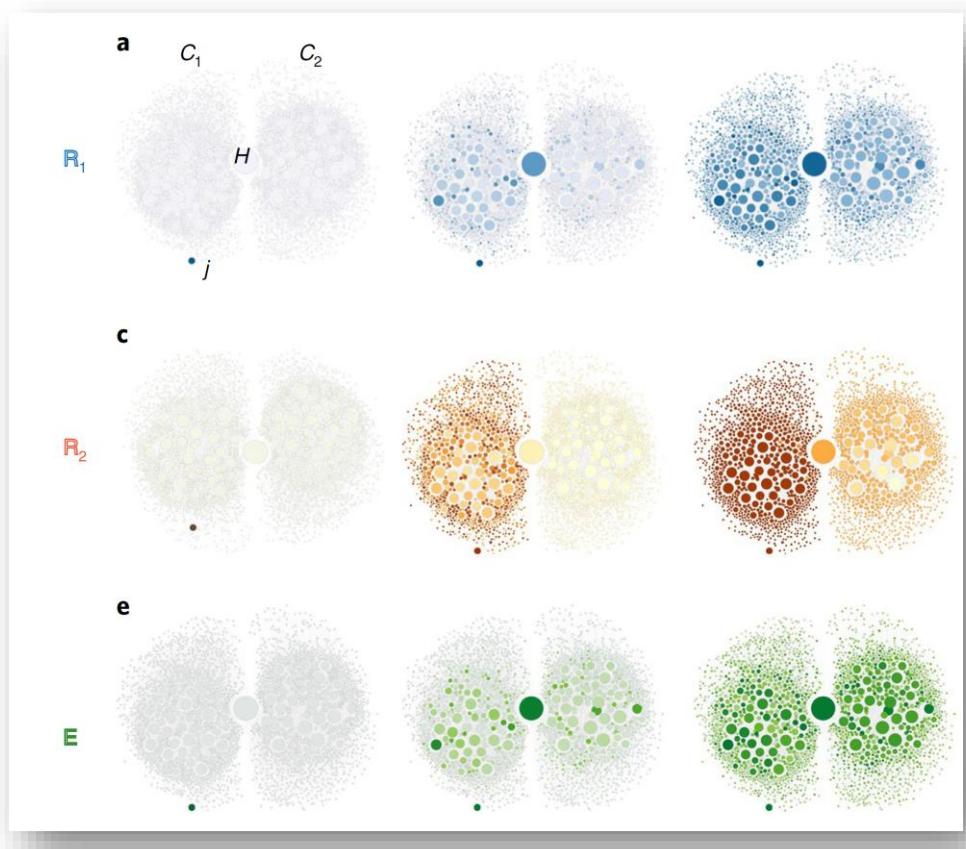
Response patterns to fixed-point perturbations

Information flow in complex networks

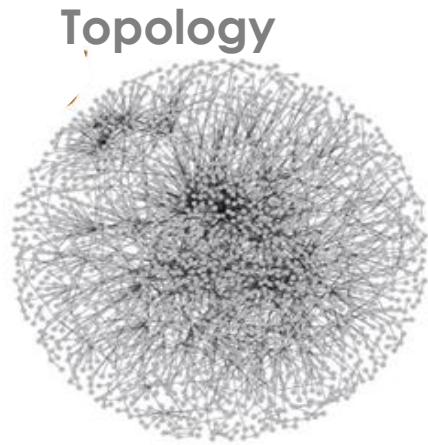
- When $T(j \rightarrow i)$
- Where $l_{ij}(t)$
- How strongly Δx_i
- How $(\mathcal{F}_i, \mathcal{F}_{ij})$



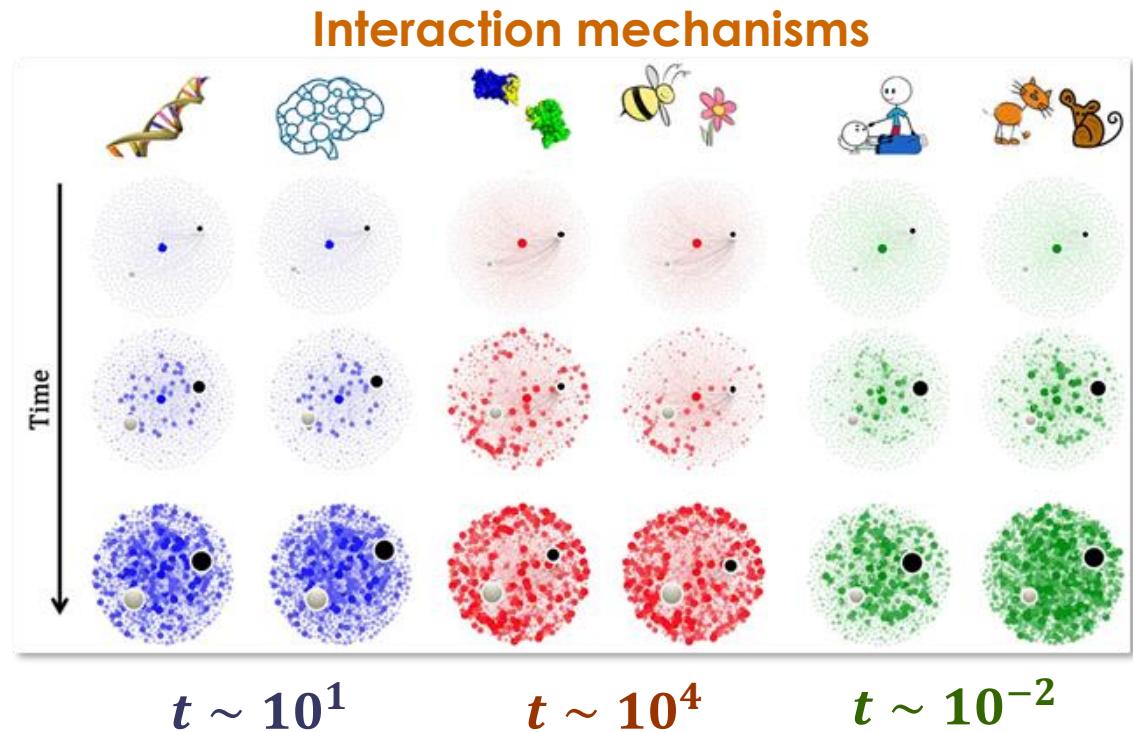
Spatiotemporal propagation



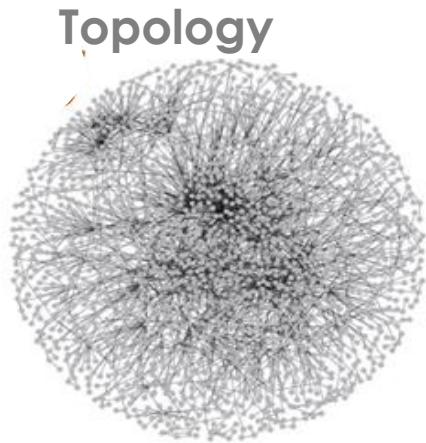
The zoo of propagation patterns



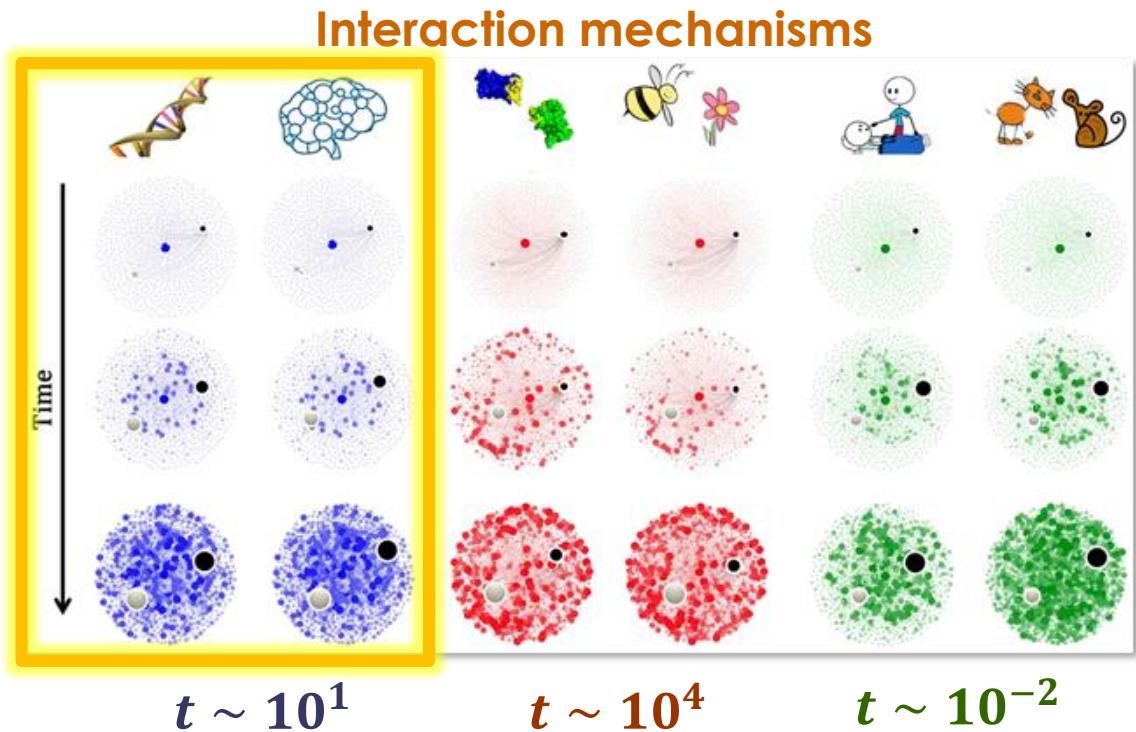
Identical networks
yield visibly distinct
propagation patterns



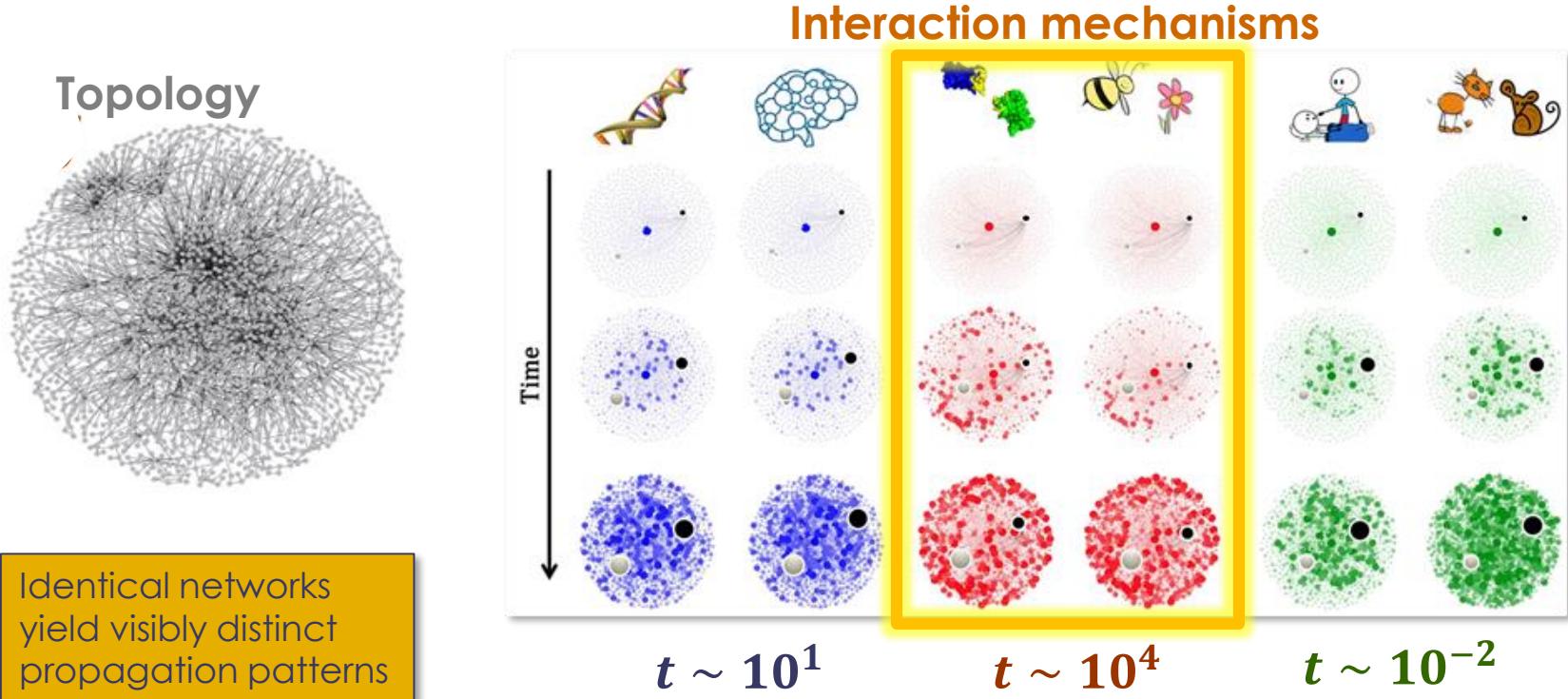
The zoo of propagation patterns



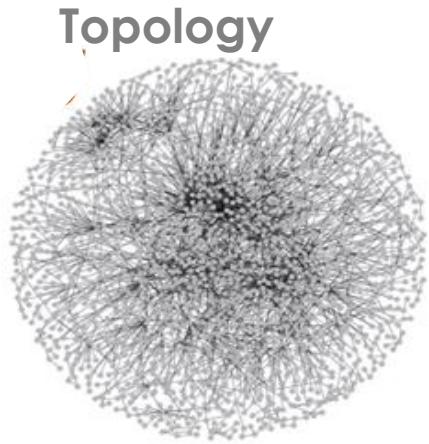
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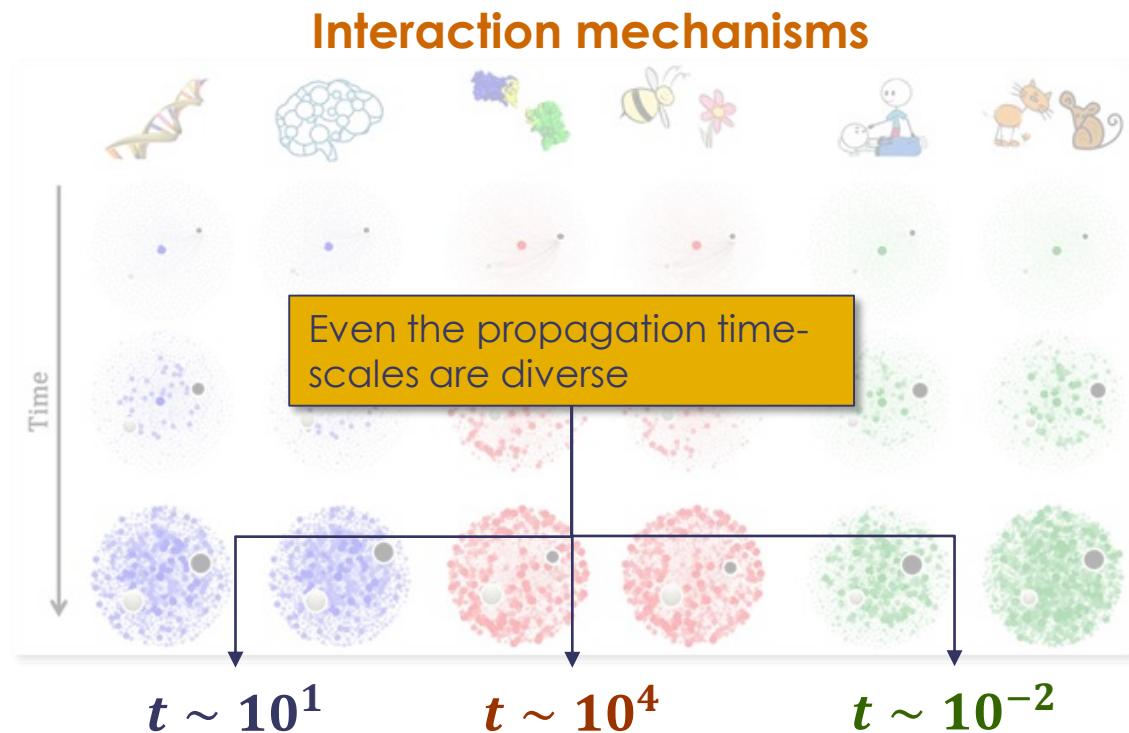
The zoo of propagation patterns



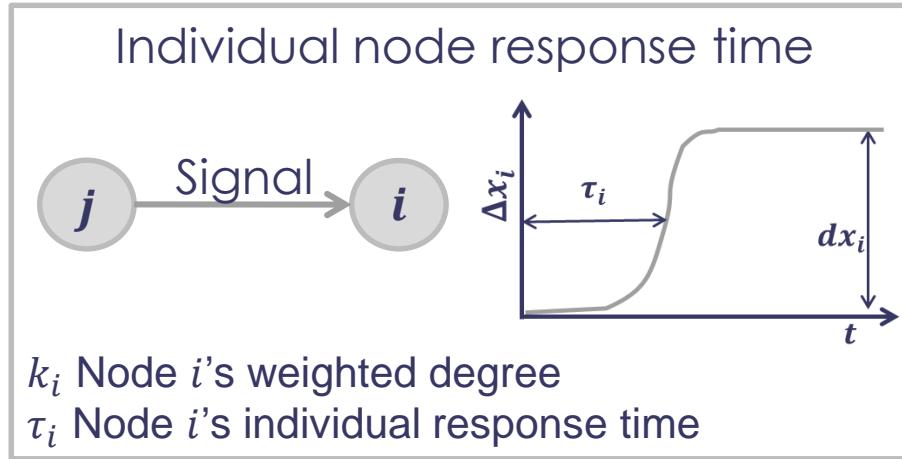
The zoo of propagation patterns



Identical networks
yield visibly distinct
propagation patterns



Taming the zoo of propagation patterns

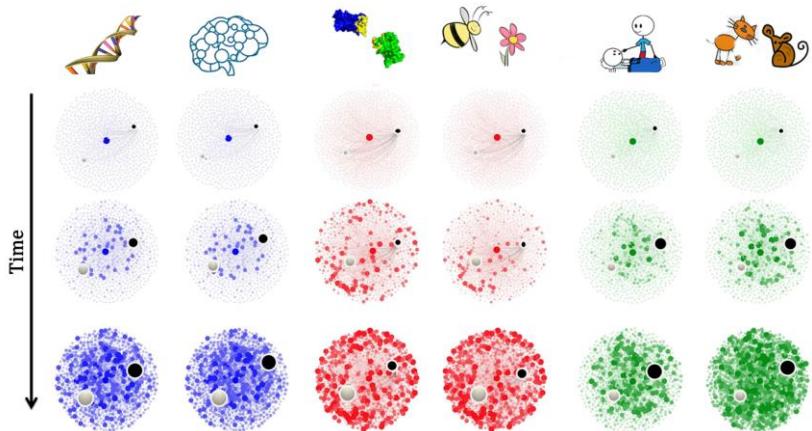


$$\tau_i \sim k_i^\theta$$

A node's intrinsic response time scales with its weighted degree

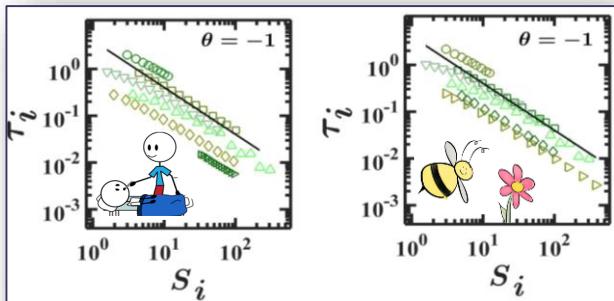
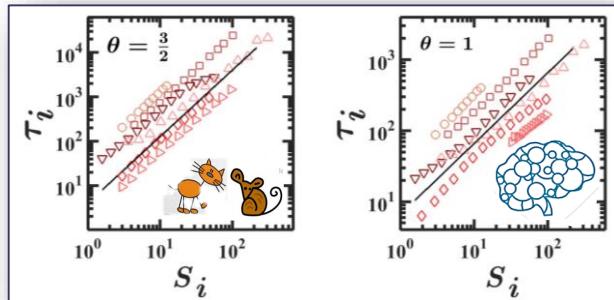
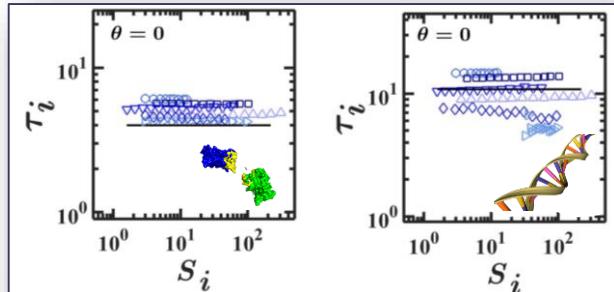
Why should you care?

Diverse & unpredictable



Universal

$$\tau_i \sim k_i^\theta$$



Why should you care?

How do we obtain the exponent θ ?

$$\frac{dx_i}{dt} = \mathbf{M}_0(x_i) + \sum_{j=1}^N A_{ij} \mathbf{M}_1(x_i) \mathbf{M}_2(x_j)$$



$$R(x) = -\frac{M_1(x)}{M_0(x)}$$

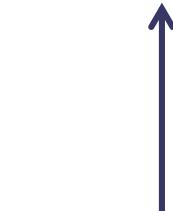
$$\tau_i \sim k_i^\theta$$

$$Y(x) = \left(\frac{d(M_1(x)R(x))}{dx} \right)^{-1}$$



$$Y(R^{-1}(x)) = \sum_{n=0}^{\infty} C_n x^{\Gamma(n)}$$

$$\theta = -2 - \Gamma(0)$$



Why should you care:

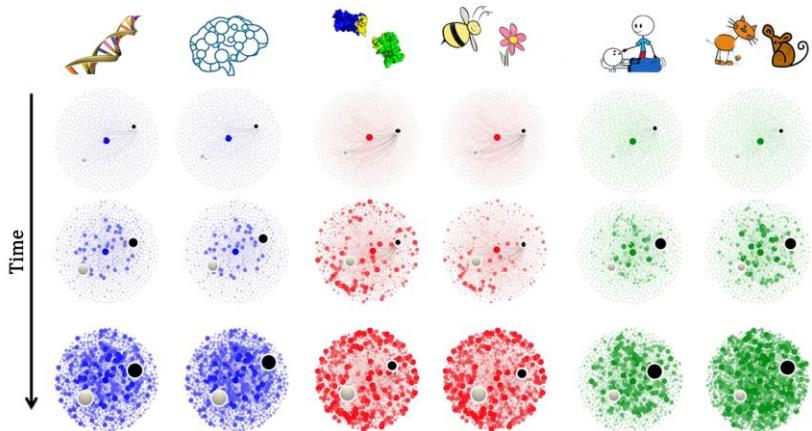
θ depends on the system's Dynamics (M_0, M_1, M_2)

Only on leading powers (through $\Gamma(0)$)

Not on coefficients (C_n)

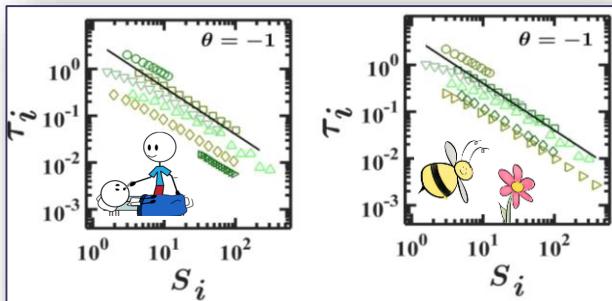
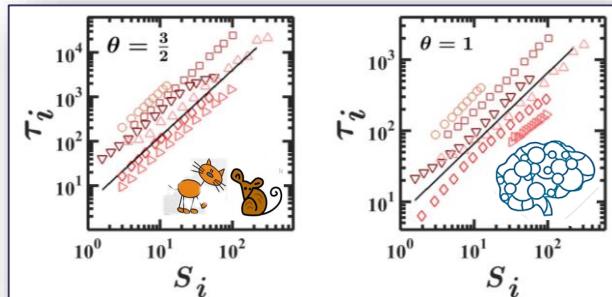
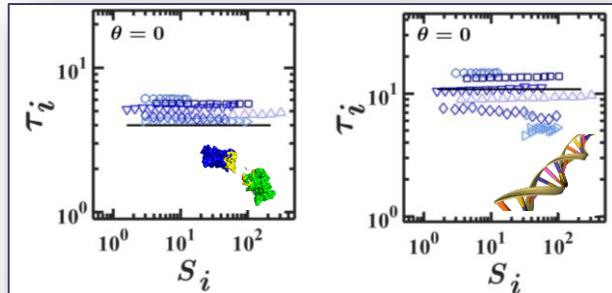
Universality

Diverse & unpredictable



Universal

$$\tau_i \sim k_i^\theta$$



Dynamic insight

Response time

Dynamic observable of interest.

$$\tau_i \sim k_i^\theta$$

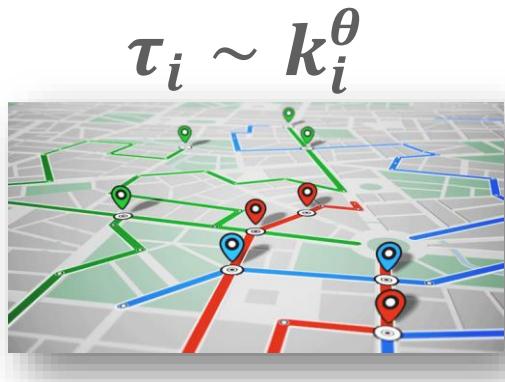
Weighted degree

Known topological element

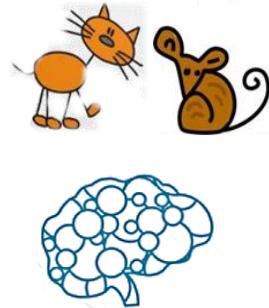
Dynamic determinant

Mapping topology into dynamics

Network GPS – how signals navigate the network



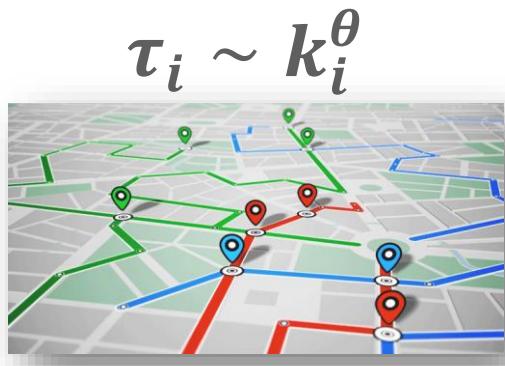
$\theta > 0$
Hubs
=
Bottlenecks



$\theta < 0$
Hubs
=
Free flow

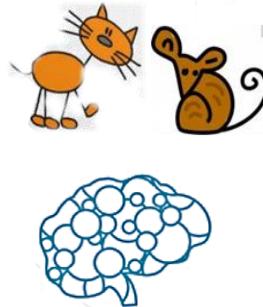


Network GPS – how signals navigate the network



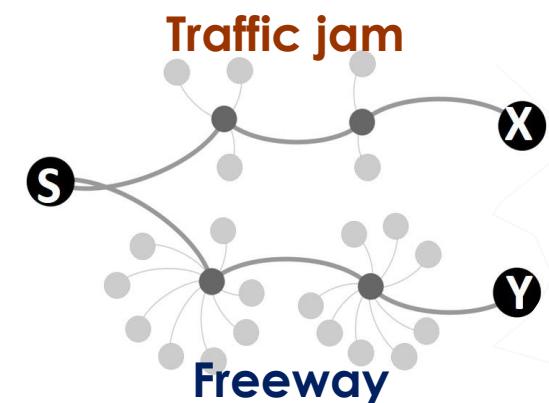
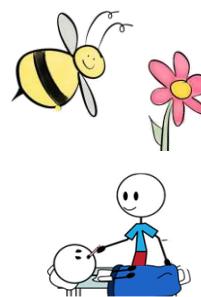
$$\theta > 0$$

Hubs
=
Bottlenecks

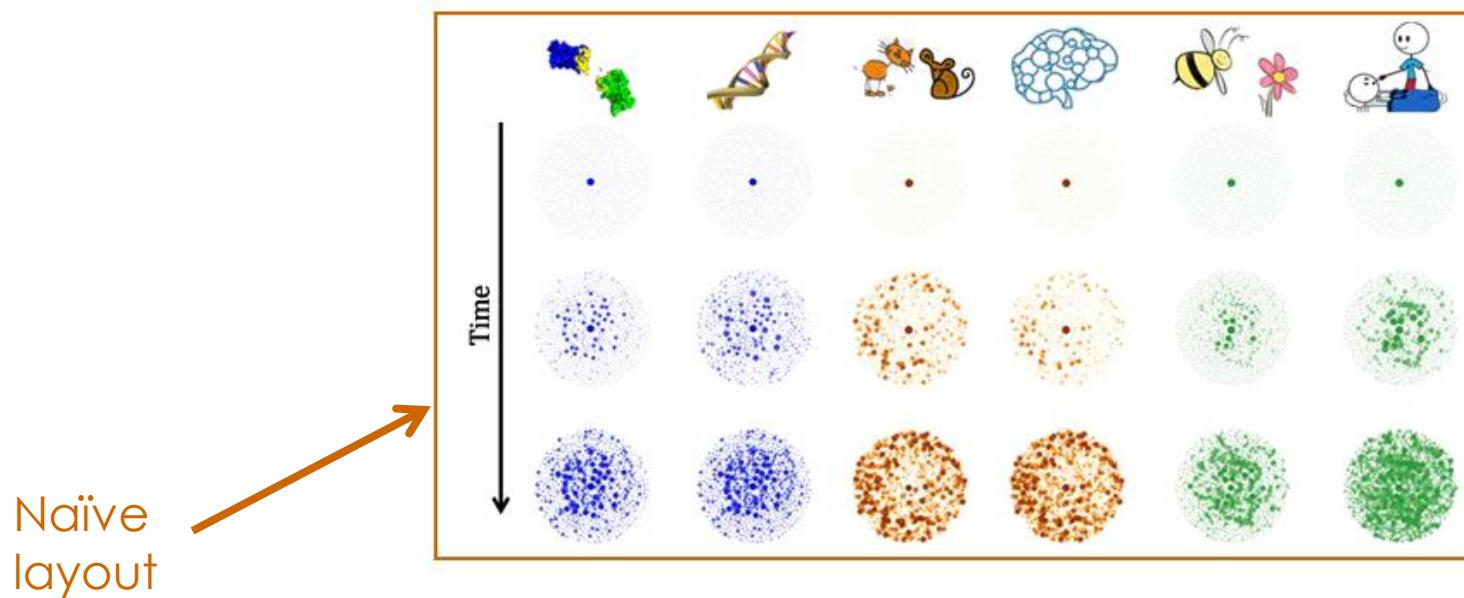


$$\theta < 0$$

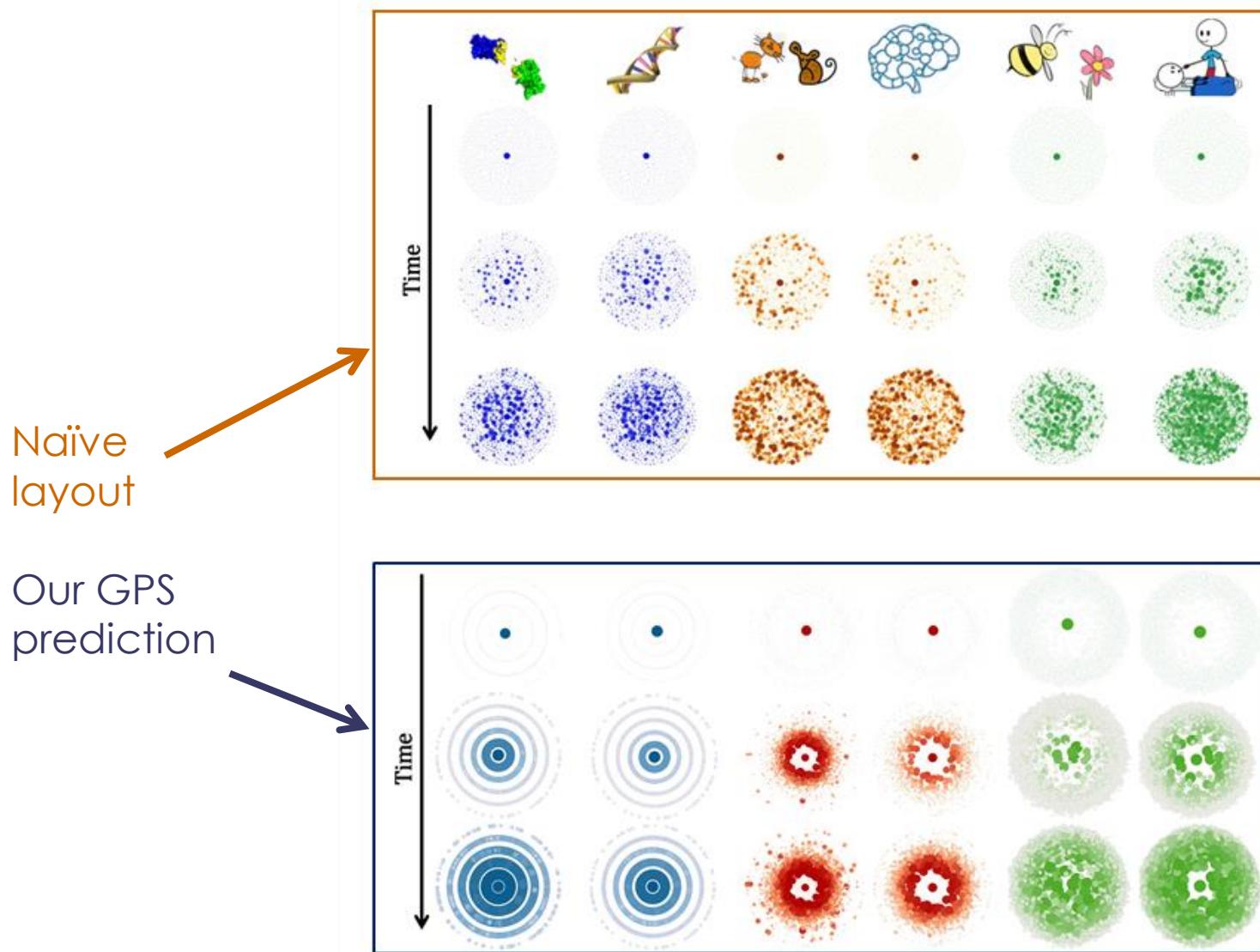
Hubs
=
Free flow



Network GPS – how signals navigate the network

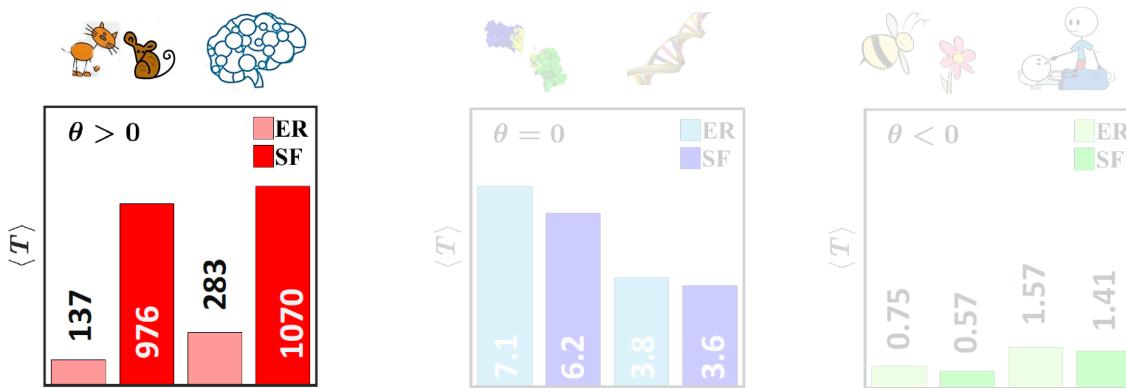


Network GPS – how signals navigate the network



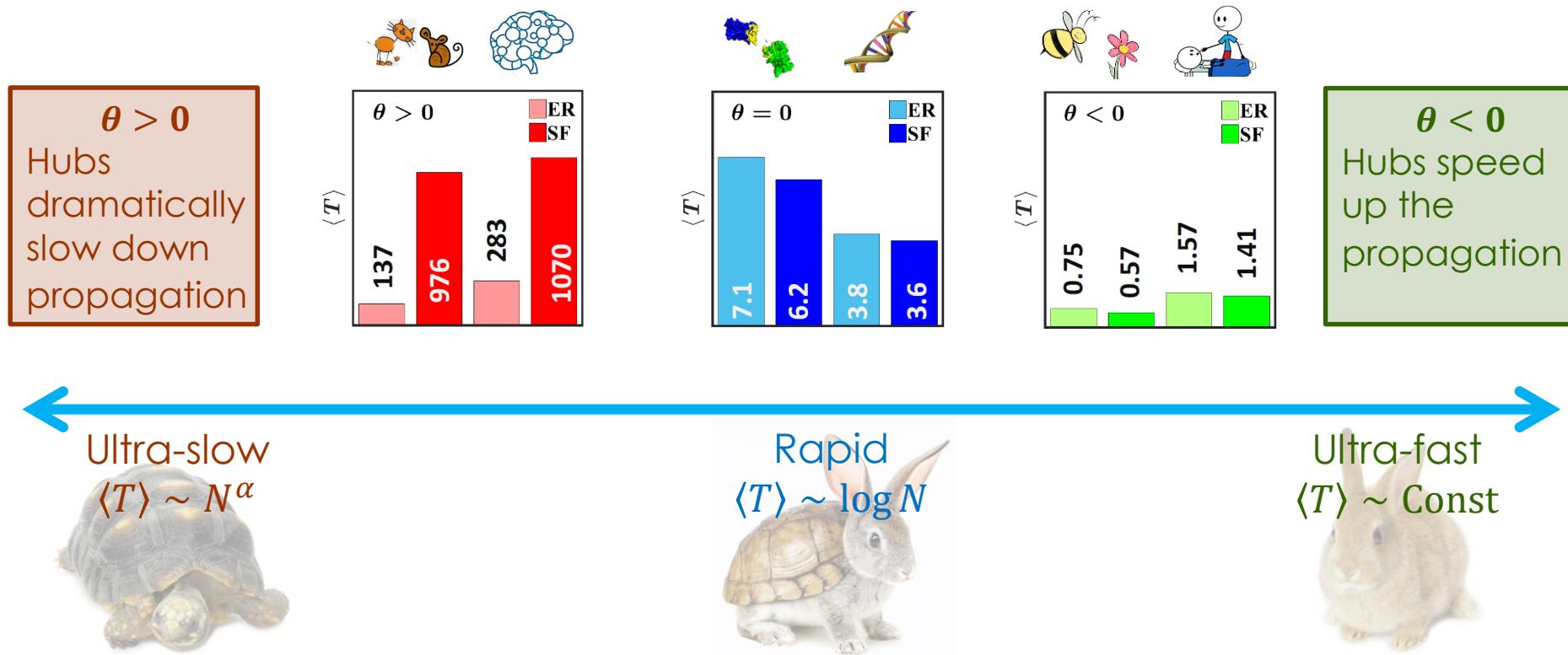
Same topology – different spreading rules

$\theta > 0$
Hubs
dramatically
slow down
propagation



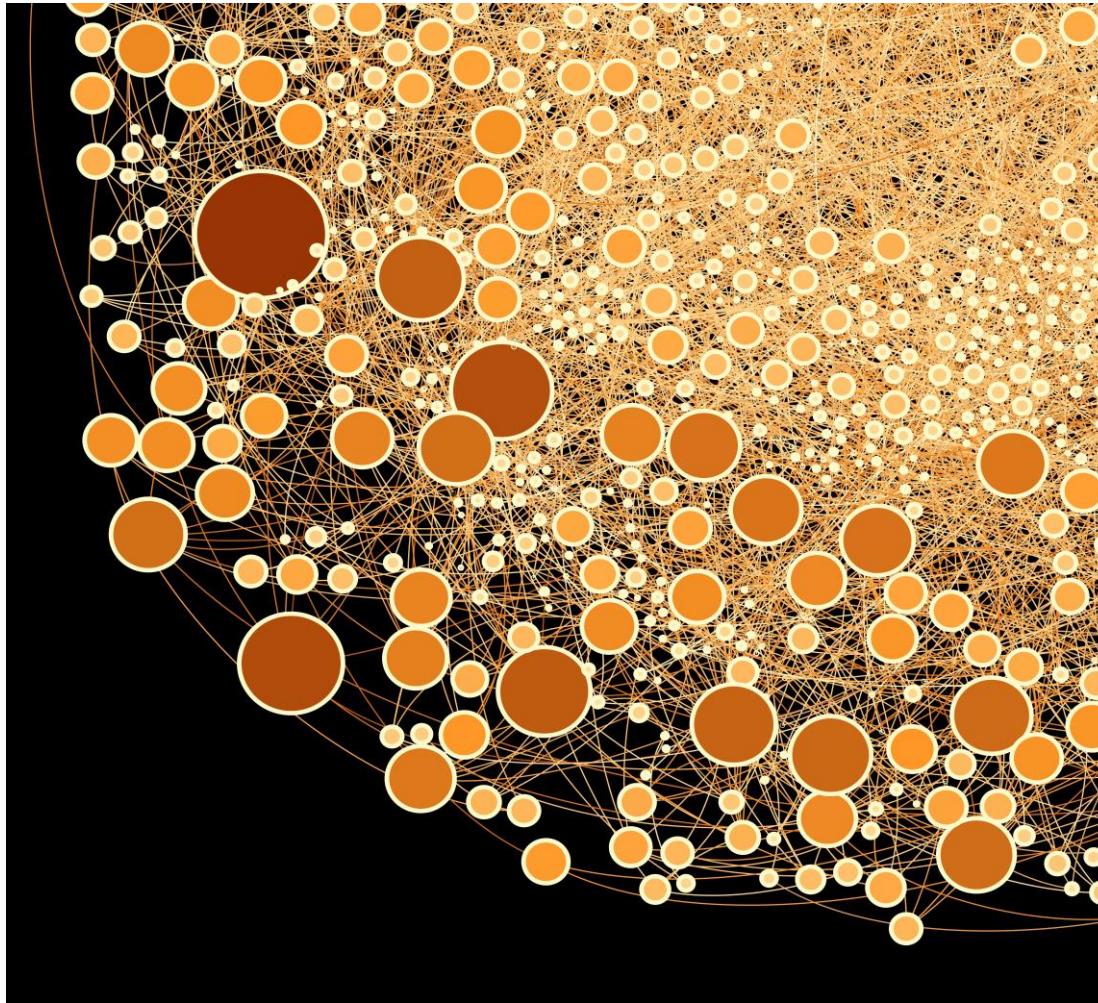
Hubs speed
up the
propagation

Same topology – different spreading rules

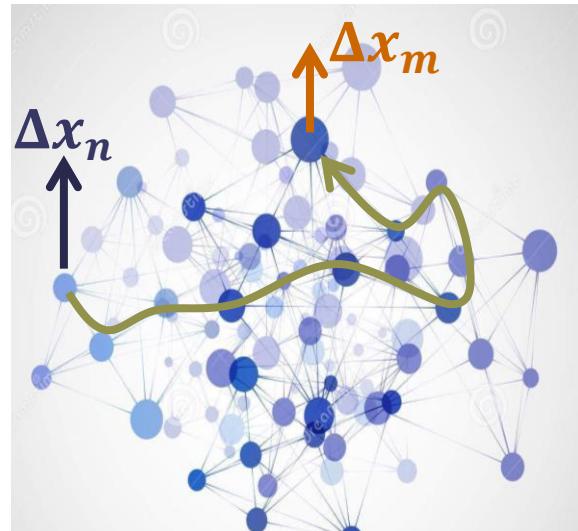


Different interpretations of scale-freeness. All boiled down to a single analytically predictable parameter θ

Flow



Information flow



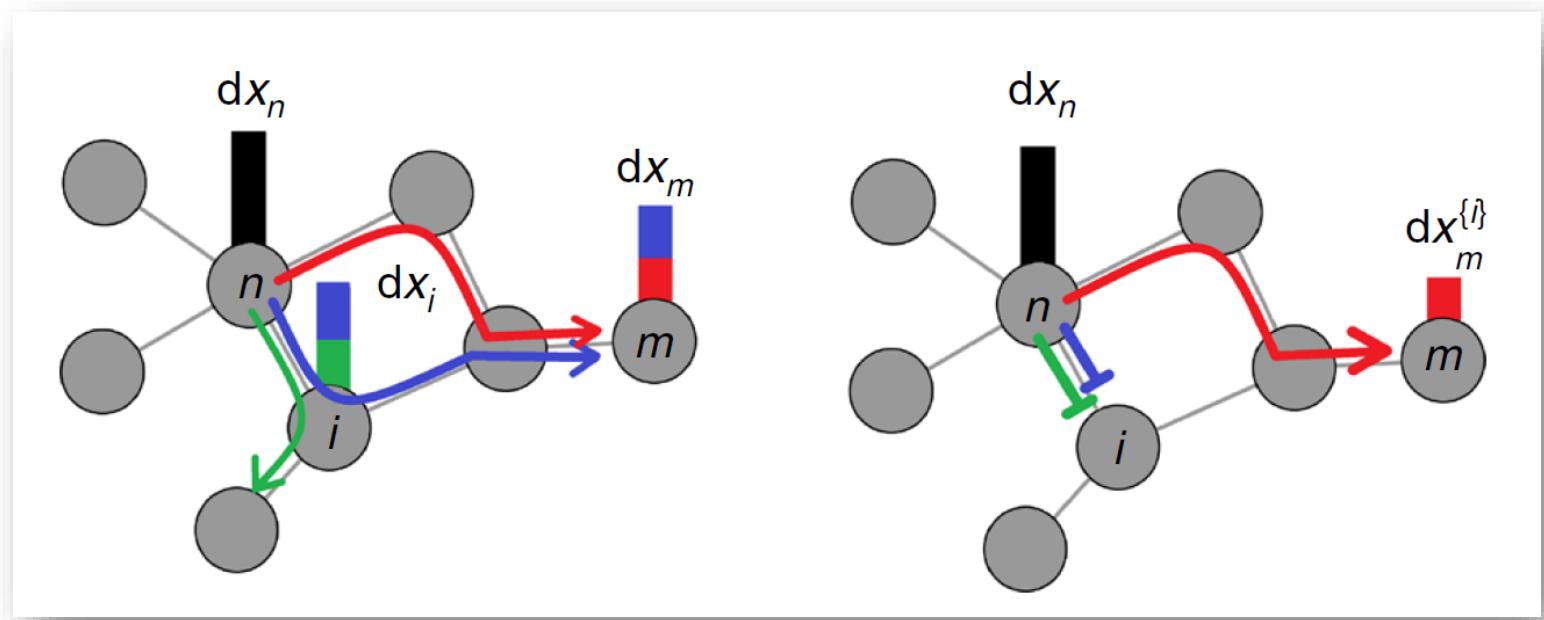
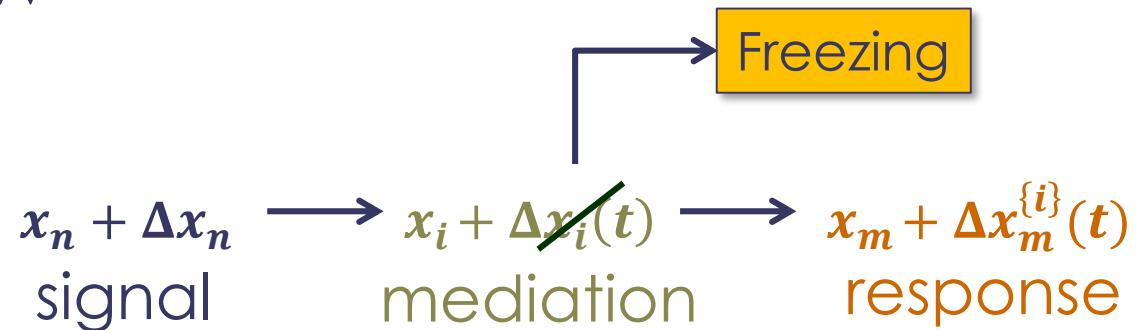
$x_n + \Delta x_n \longrightarrow x_i + \Delta x_i(t) \longrightarrow x_m + \Delta x_m(t)$

signal mediation response

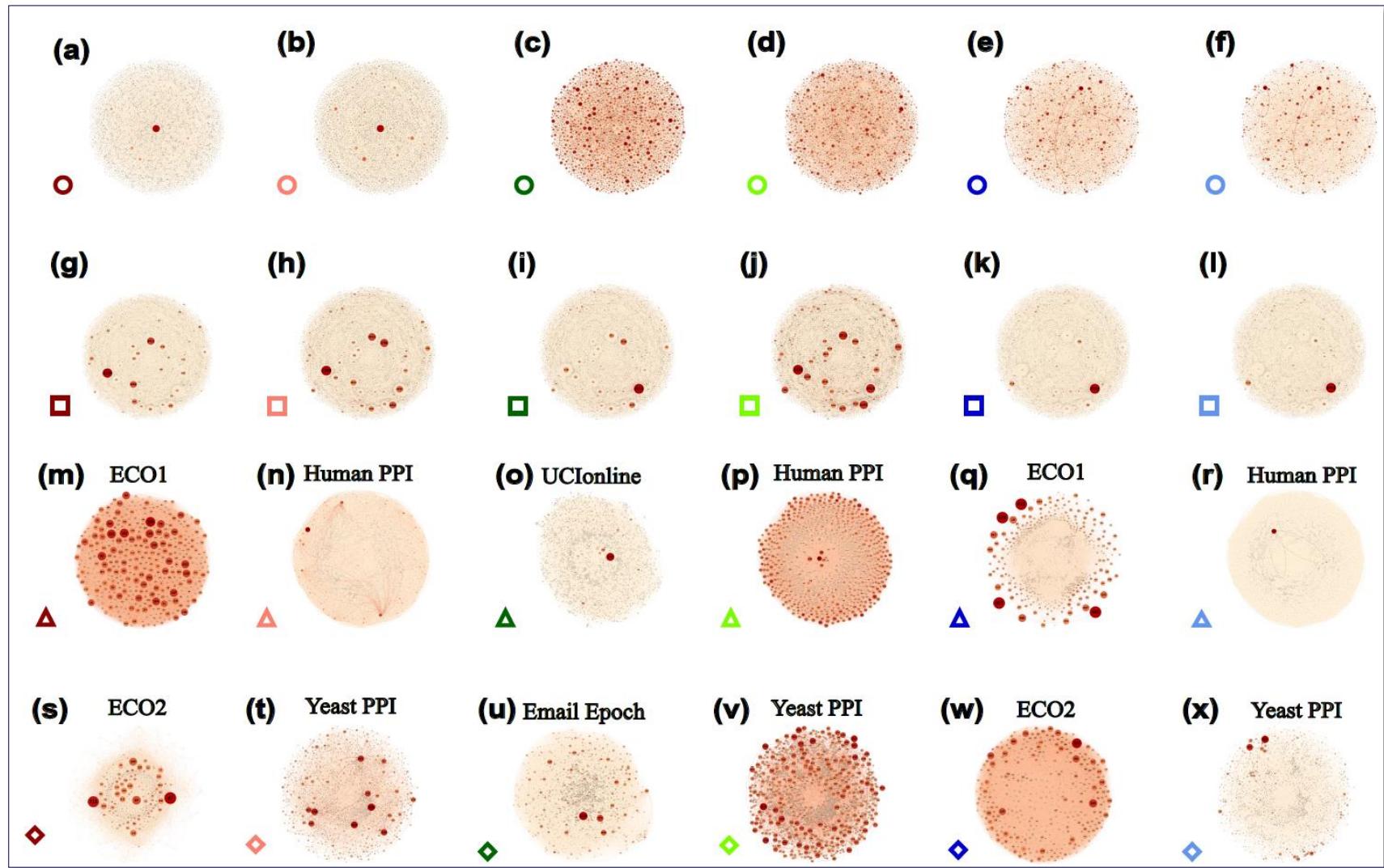
Node flow \mathcal{F}_i : how effective is each node in *transferring* information?

Link flow \mathcal{F}_{ij} : How effective is each link, pathway?

Information flow



The zoo of information flow patterns



Taming the zoo of information flow patterns

$$\mathcal{F}_i \sim k_{i,\text{out}} k_{i,\text{in}}^{\omega-1}$$

$$\mathcal{F}_{ij} \sim A_{ij} k_{i,\text{out}} k_{i,\text{in}}^{\xi-1} k_{j,\text{in}}^{\xi}$$

Node/link flow

Dynamic function
of interest.

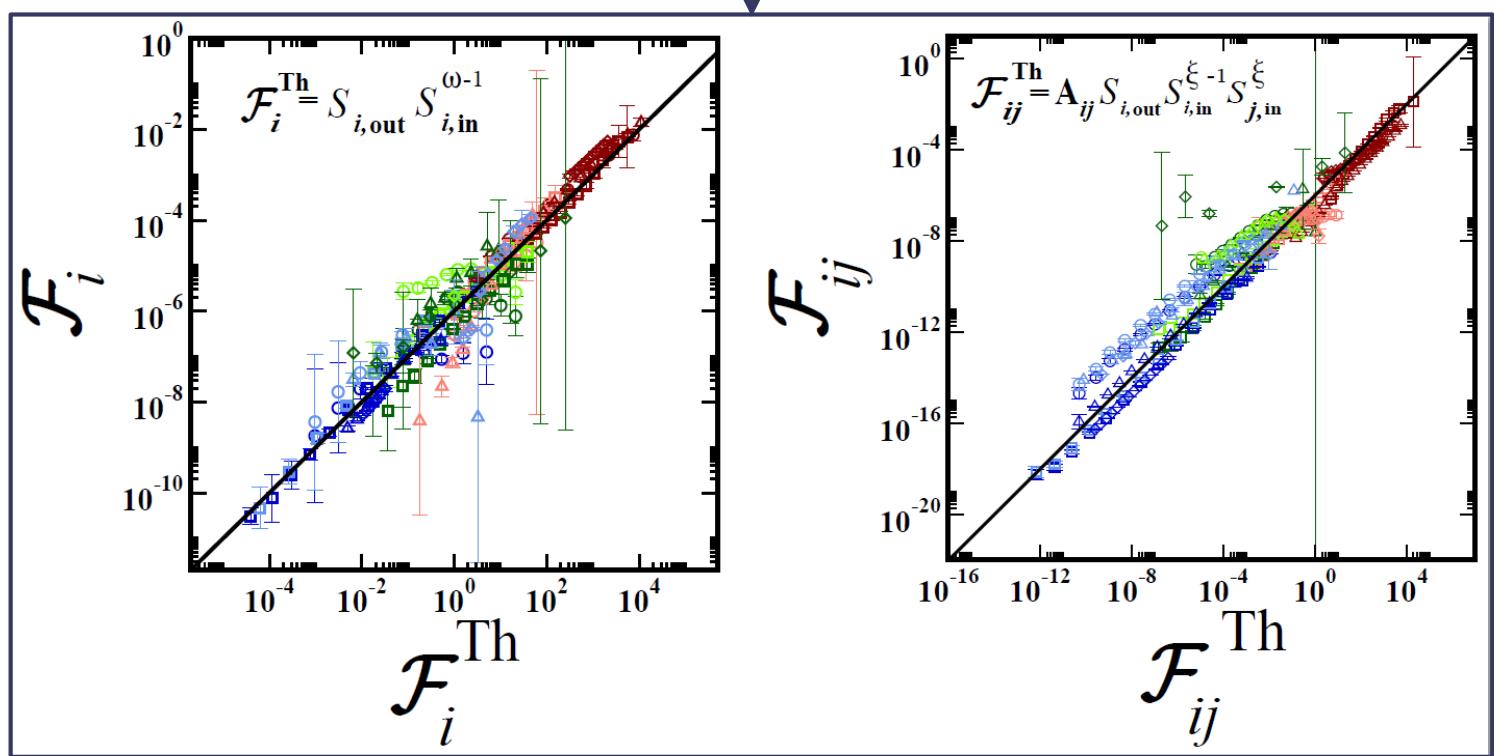
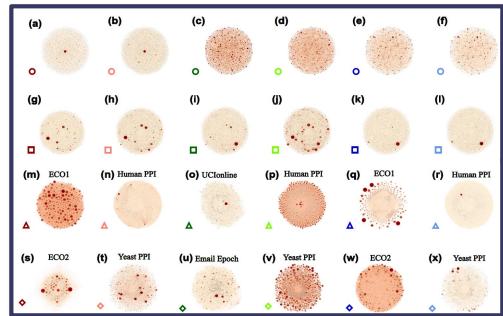
**Dynamic
determinants**

Mapping topology into
dynamics

$\mathcal{F}_i, \mathcal{F}_{ij}, k_{\text{in/out}}$, ω, ξ

Weighted in/out degrees
Known topological elements

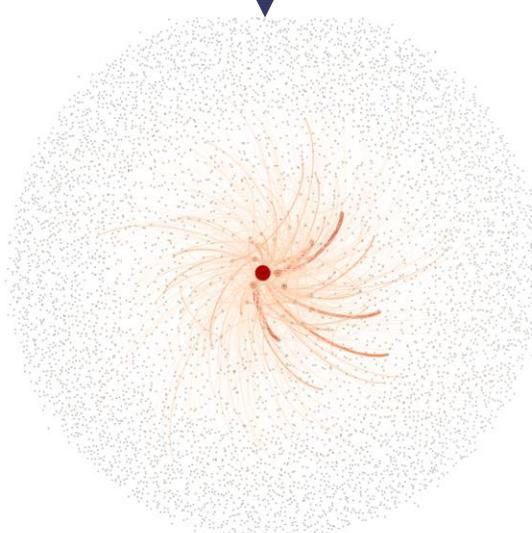
The ~~zoo~~ universal information flow patterns



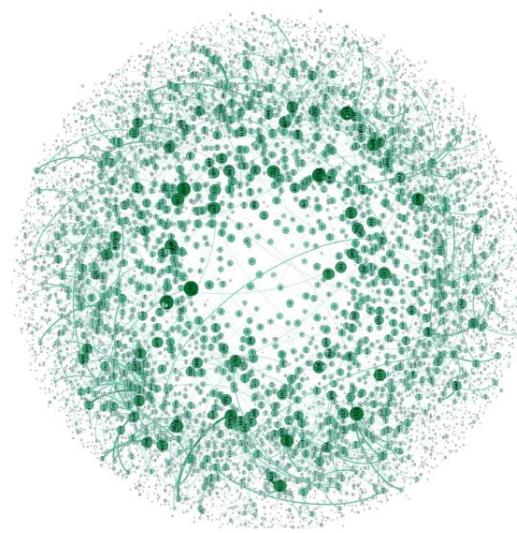
Universal classes of information flow patterns

$$\mathcal{F}_i \sim k_{i,\text{out}} k_{i,\text{in}}^{\omega-1}$$

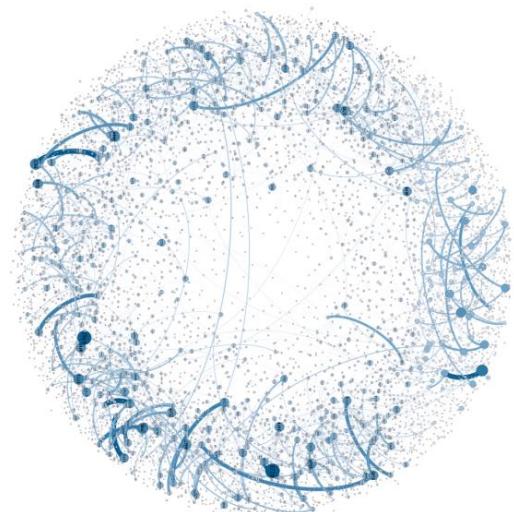
$$\mathcal{F}_{ij} \sim A_{ij} k_{i,\text{out}} k_{i,\text{in}}^{\xi-1} k_{j,\text{in}}^\xi$$



Hub centric

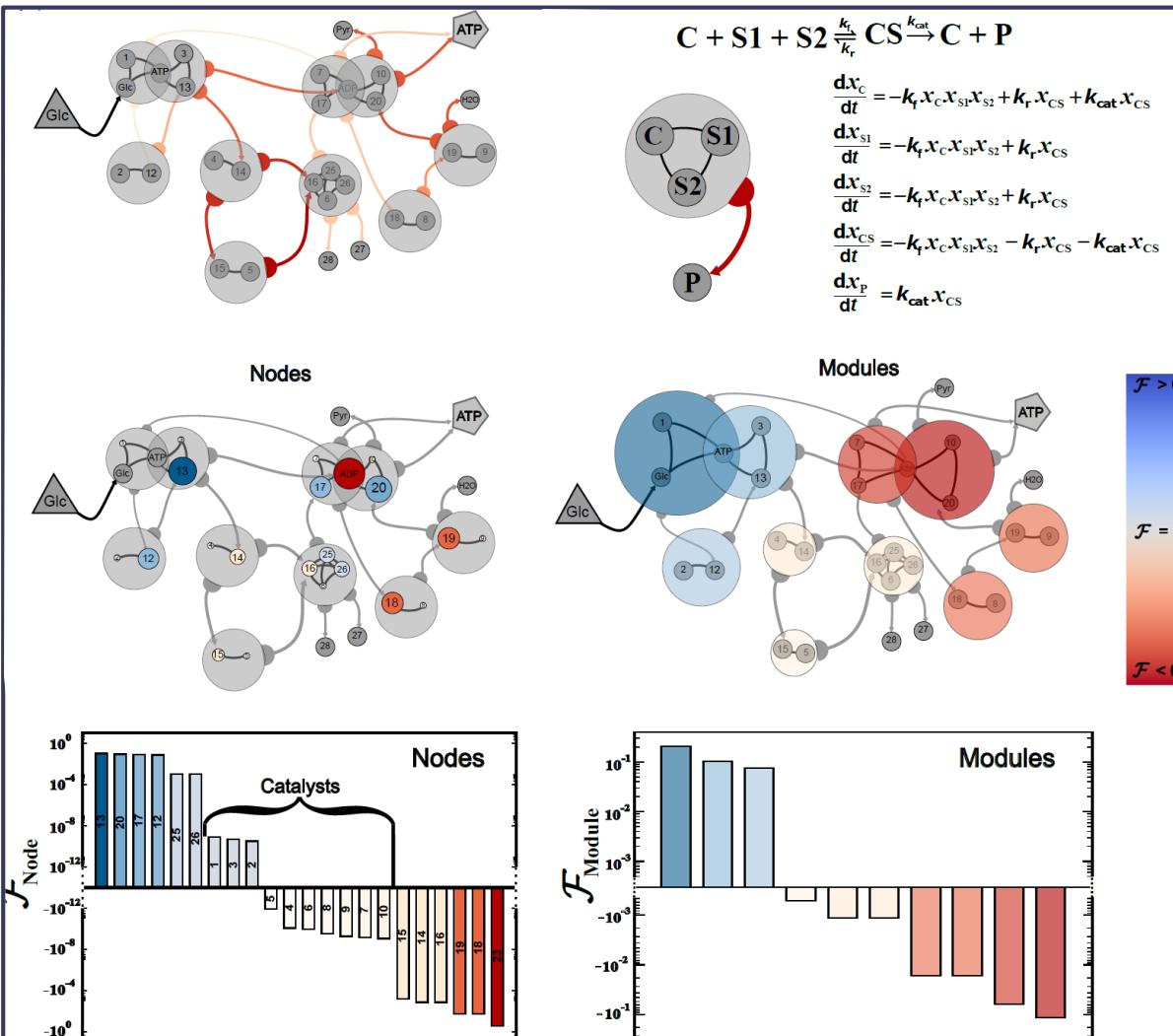


Egalitarian



Peripheral

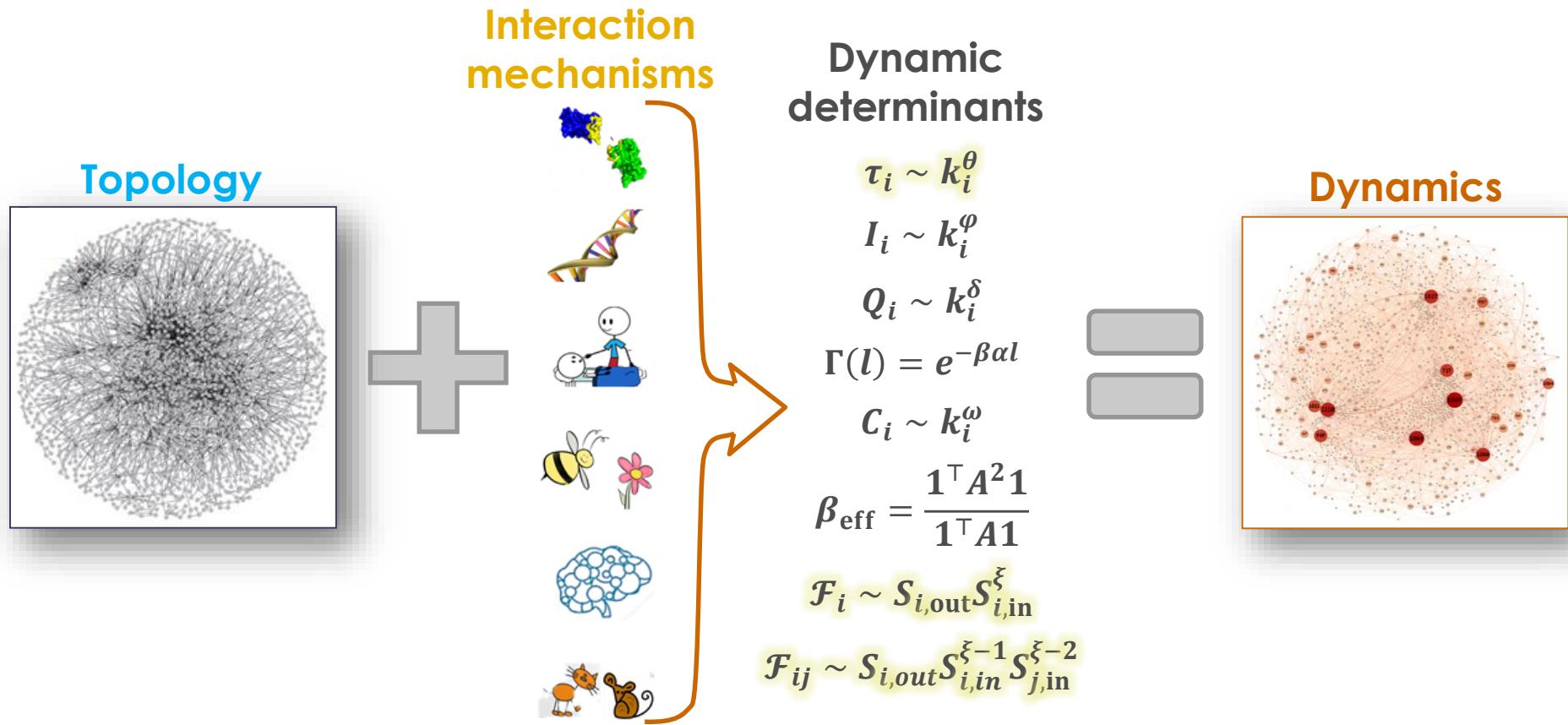
Flow analysis in Glycolysis: what is a biological network?



Metabolism: Designed to push the mean information flow towards zero.

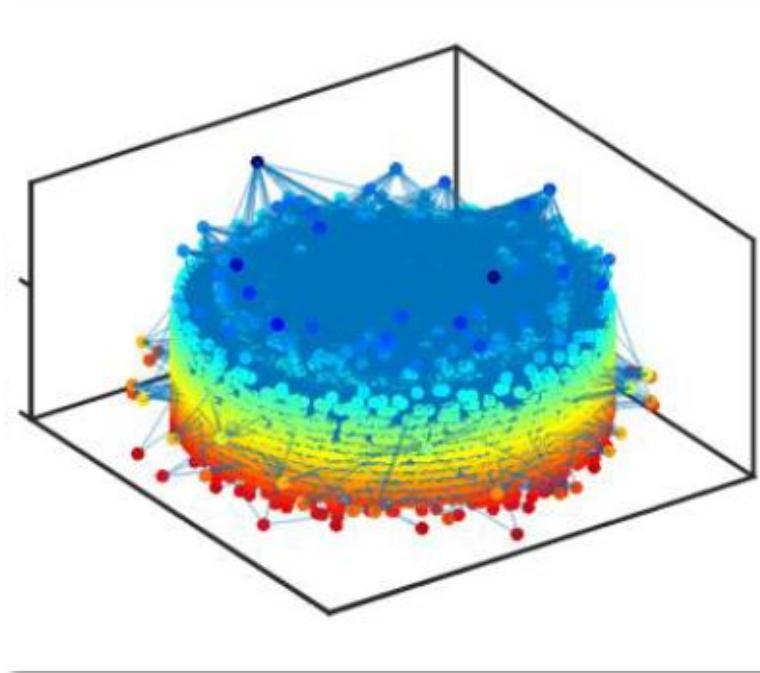
Output (response) independent of Input (perturbation)

Dictionary of network dynamics

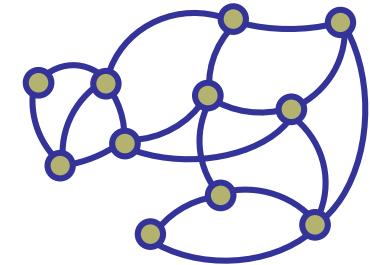
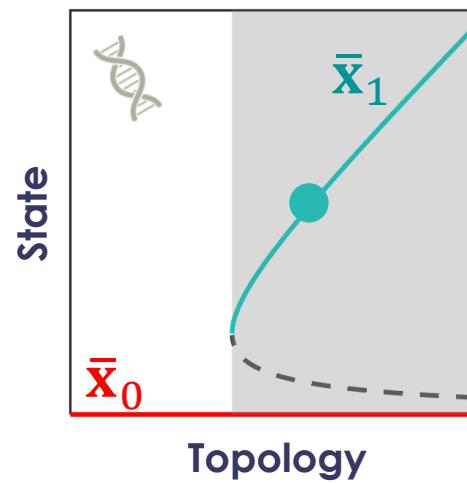
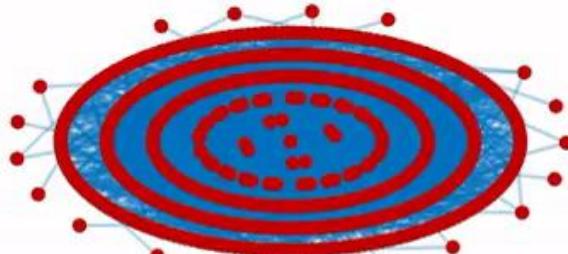


Microscopic Diversity condenses into a discrete set of
Universality classes that determine how
Topology translates into Dynamics

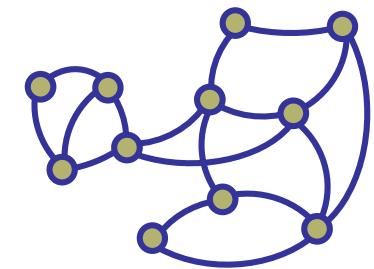
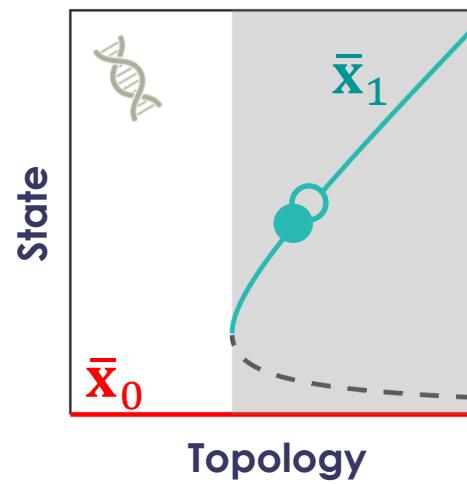
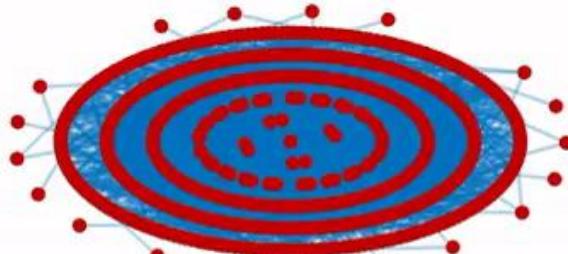
Recoverability



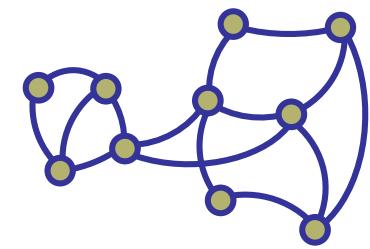
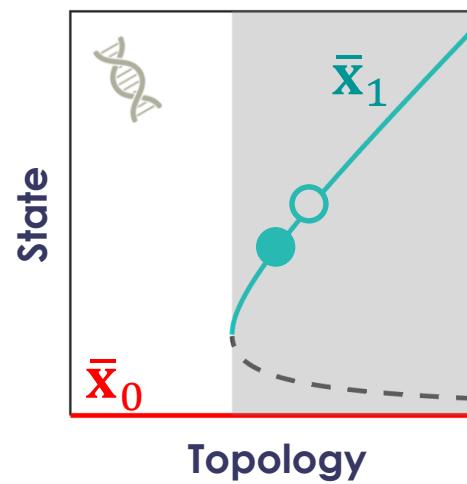
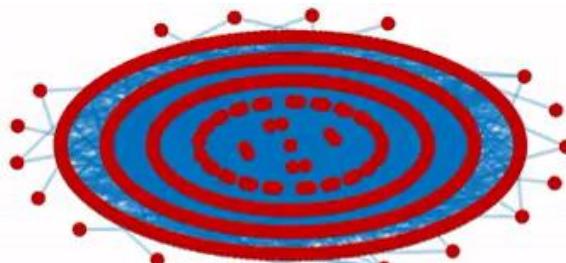
Dynamic transitions



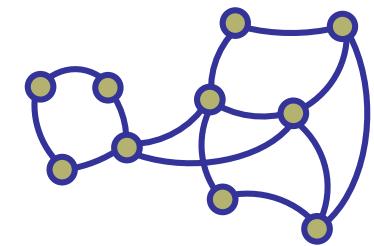
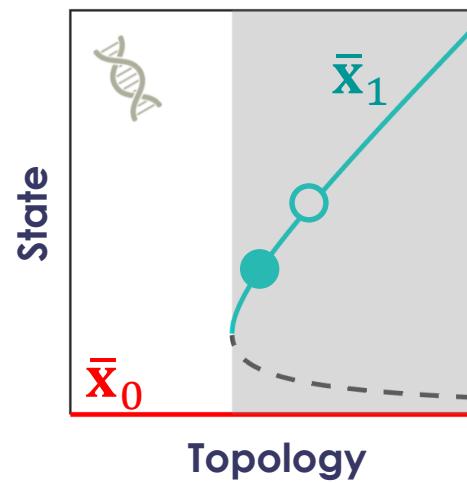
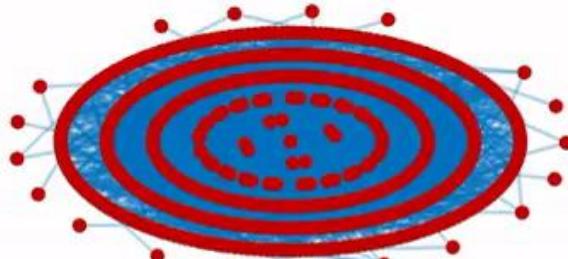
Dynamic transitions



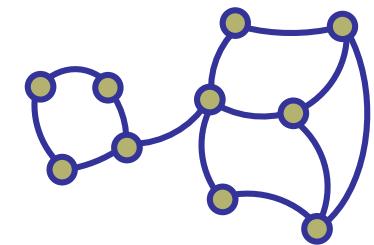
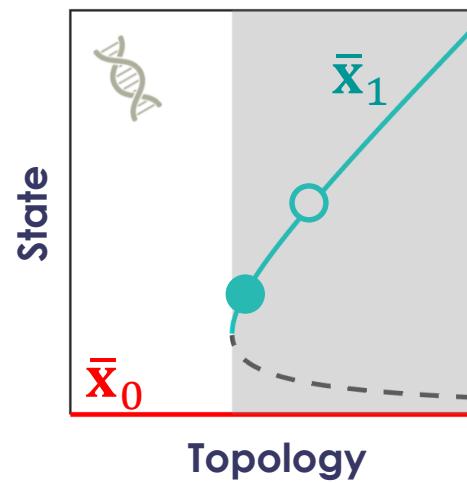
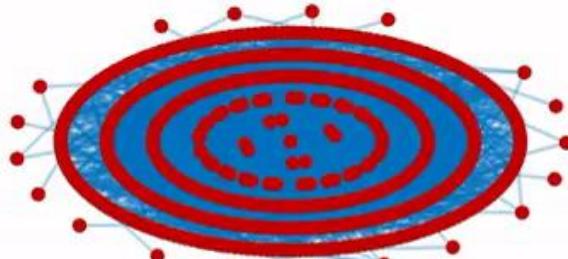
Dynamic transitions



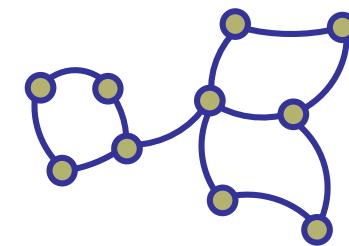
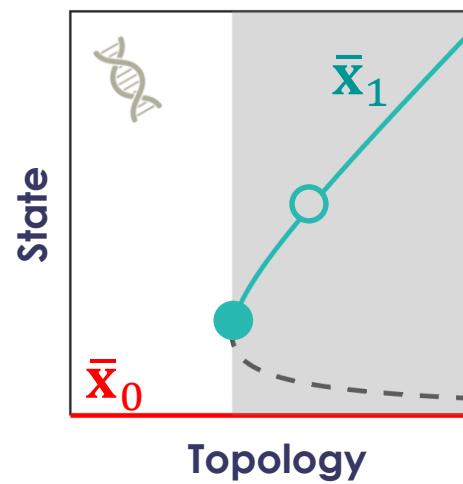
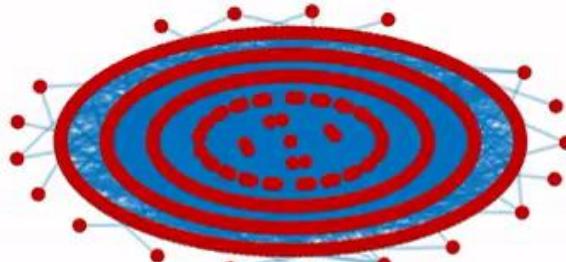
Dynamic transitions



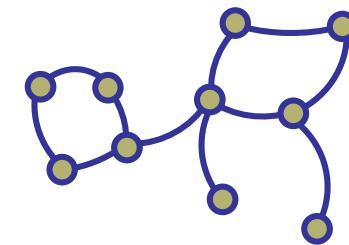
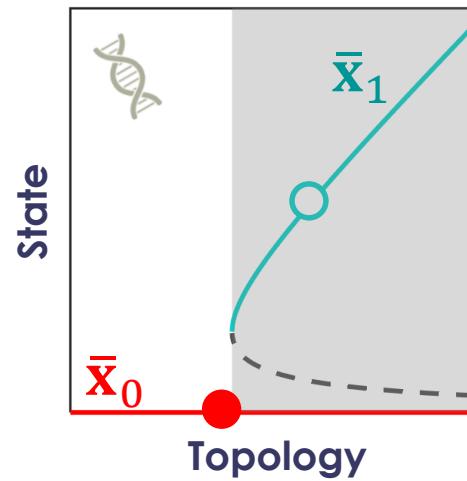
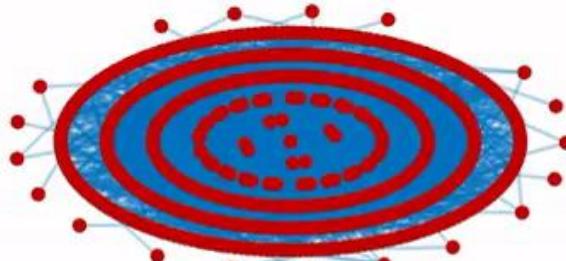
Dynamic transitions



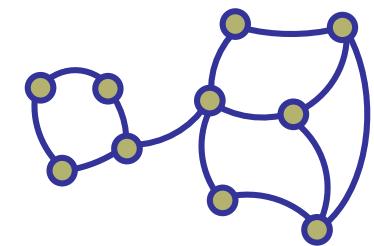
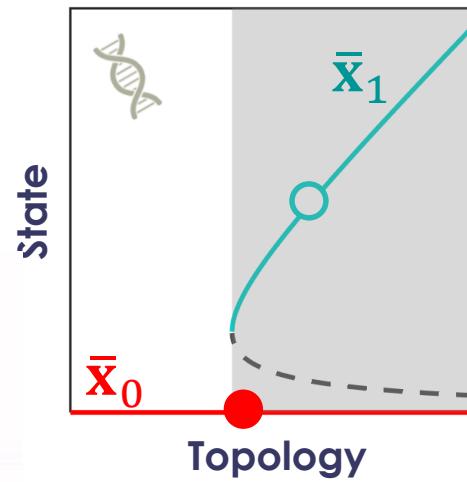
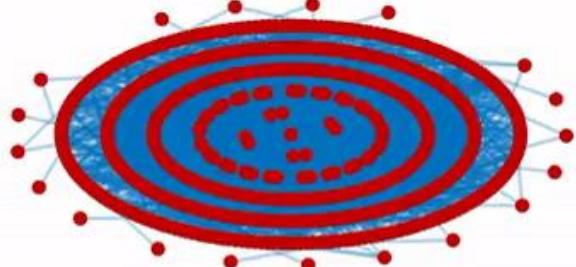
Dynamic transitions



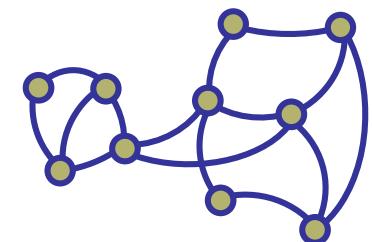
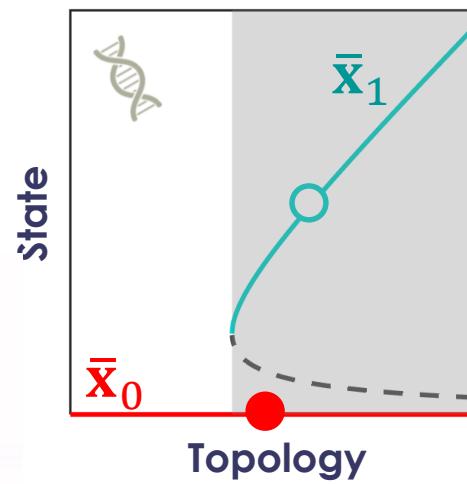
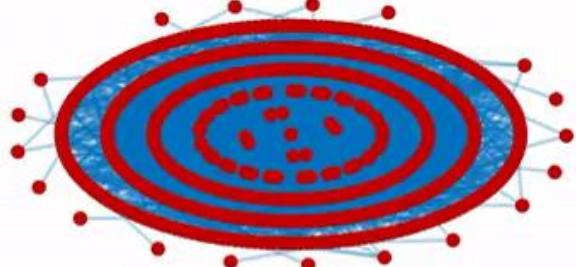
Dynamic transitions



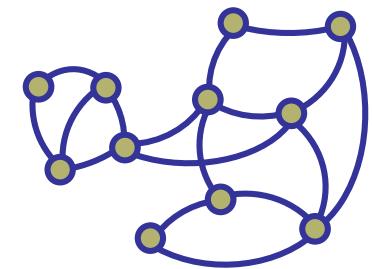
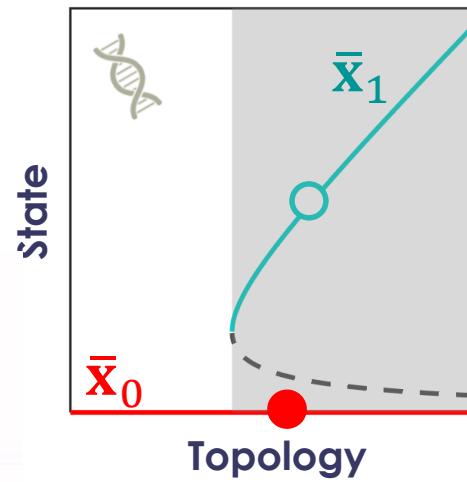
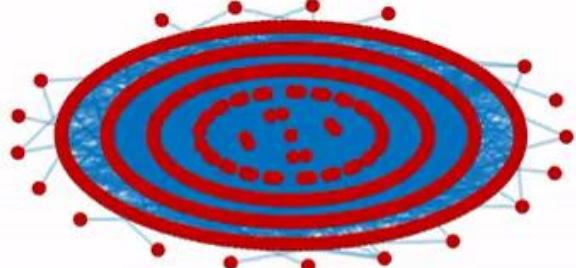
Dynamic transitions - irreversible



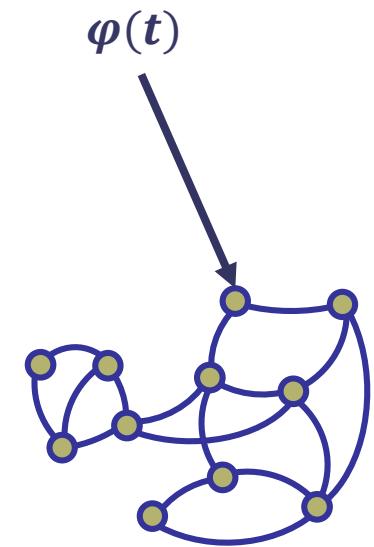
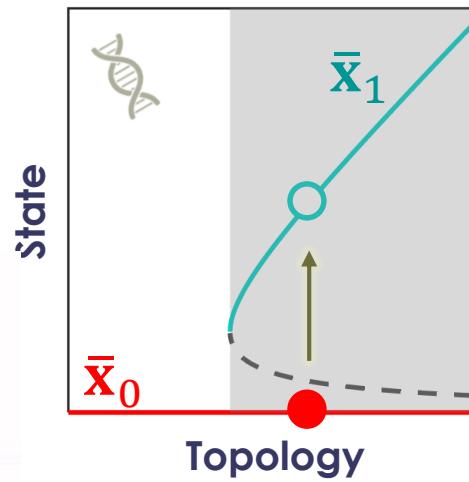
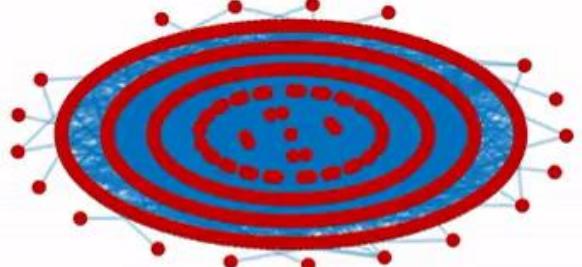
Dynamic transitions - irreversible



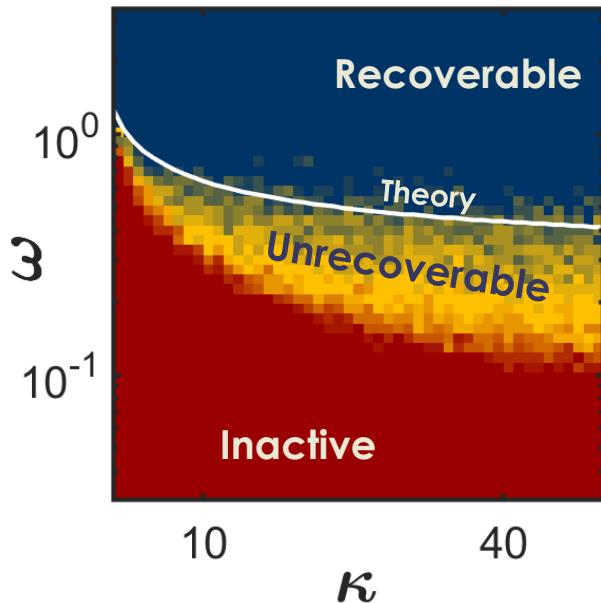
Dynamic transitions - irreversible



Reigniting the network activity

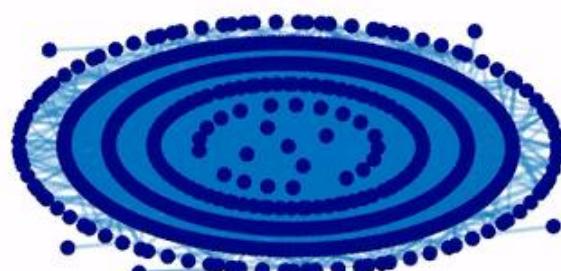
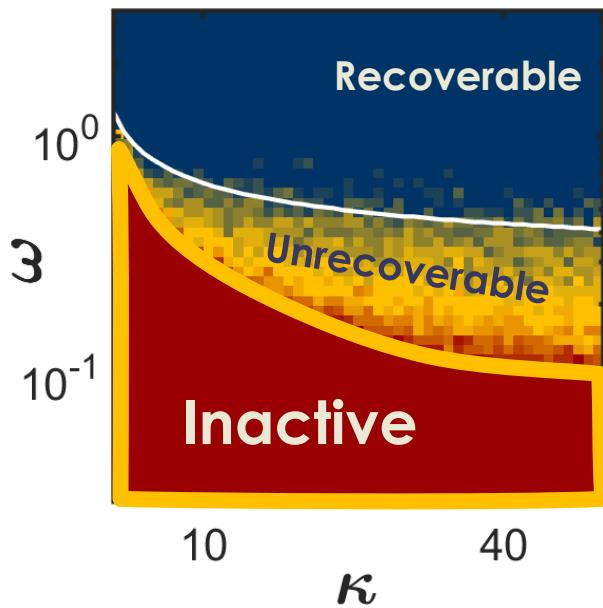


The recoverable phase

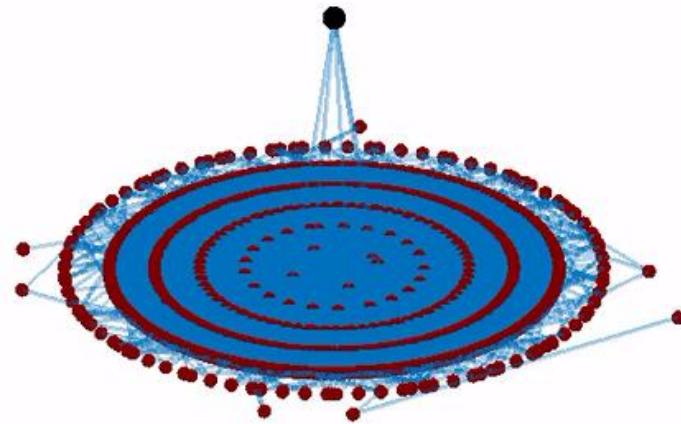
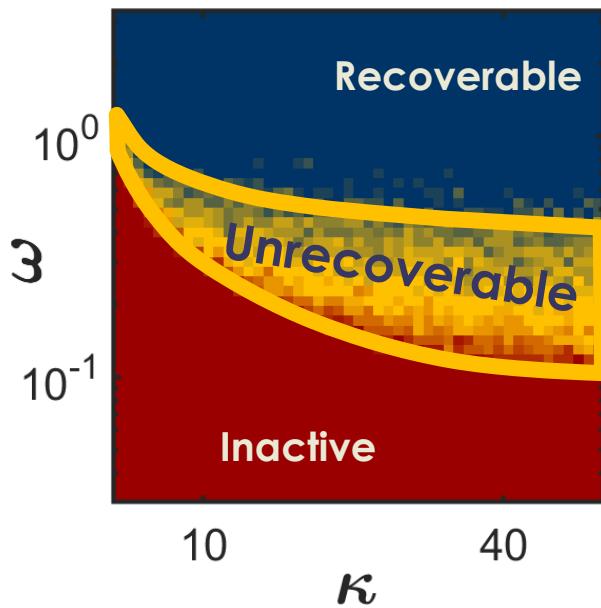


Can you reignite a failed system by controlling just one node?

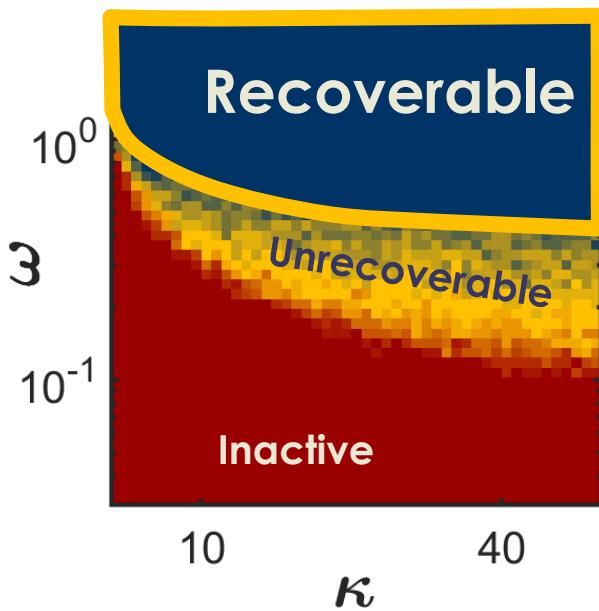
The recoverable phase



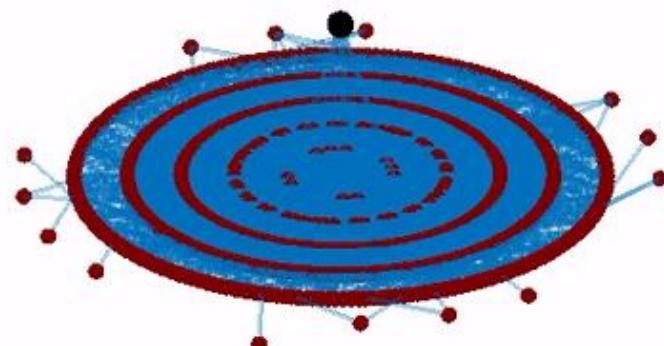
The recoverable phase



The recoverable phase



Single node reigniting –
reviving the failed system by
activating one node



Theory of network dynamics was brought to you by



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